

A Comparison of Expressive Speech Synthesis Approaches based on Neural Network

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ABSTRACT

Adaptability and controllability in changing speaking styles and speaker characteristics are the advantages of deep neural networks (DNNs) based statistical parametric speech synthesis (SPSS). This paper presents a comprehensive study on the use of DNNs for expressive speech synthesis with a small set of emotional speech data. Specifically, we study three typical model adaptation approaches: (1) retraining a neural model by emotion-specific data (retrain), (2) augmenting the network input using emotion-specific codes (code) and (3) using emotion-dependent output layers with shared hidden layers (multi-head). Long-short term memory (LSTM) networks are used as the acoustic models. Objective and subjective evaluations have demonstrated that the multi-head approach consistently outperforms the other two approaches with more natural emotion delivered in the synthesized speech.

CCS CONCEPTS

• Information systems → Speech / audio search; • Computing methodologies → Neural networks;

KEYWORDS

Statistical parametric speech synthesis; expressive speech synthesis; text-to-speech; neural networks; retrain; code; multi-head network

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1 INTRODUCTION

Deep neural networks (DNNs) have become the main stream in a variety of speech processing tasks, including speech synthesis. Many researches have indicated that DNNs considerably outperform hidden Markov models (HMMs) in statistical parametric speech synthesis (SPSS) [1–4]. Besides, recent end-to-end approaches, together with the WaveNet vocoder [5], have shown exciting improvements in generating natural human sounding [6–9].

The quality and naturalness of the synthesized speech have been significantly improved since the use of DNNs, but the expressiveness still lags far behind. The demand for expressive speech synthesis is increasing greatly for a number of applications, such as audiobook narration, news readers and conversational assistants. DNNs are well known for their adaptability and controllability with a small amount of target training data at hand. Given a base model, e.g., a neural network acoustic model trained using a large set of neutral speech, the target model can be achieved by adapting the base model using a small set of data from the target (e.g., a new speaker or an emotional style).

During the past years, significant efforts have been made to control the speaker variability. Wu *et al.* [10] conducted a systematic study of speaker adaptation techniques, including augmenting a low-dimensional speaker identity vector with linguistic features, performing model adaptation to scale the hidden activation weights, and conducting a feature space transformation. Zhao *et al.* [11] presented a comprehensive study on the use of speaker identity vectors, namely, *i*-vectors and speaker codes. Specifically, Hojo *et al.* [12] compared the performance of feeding speaker codes into different

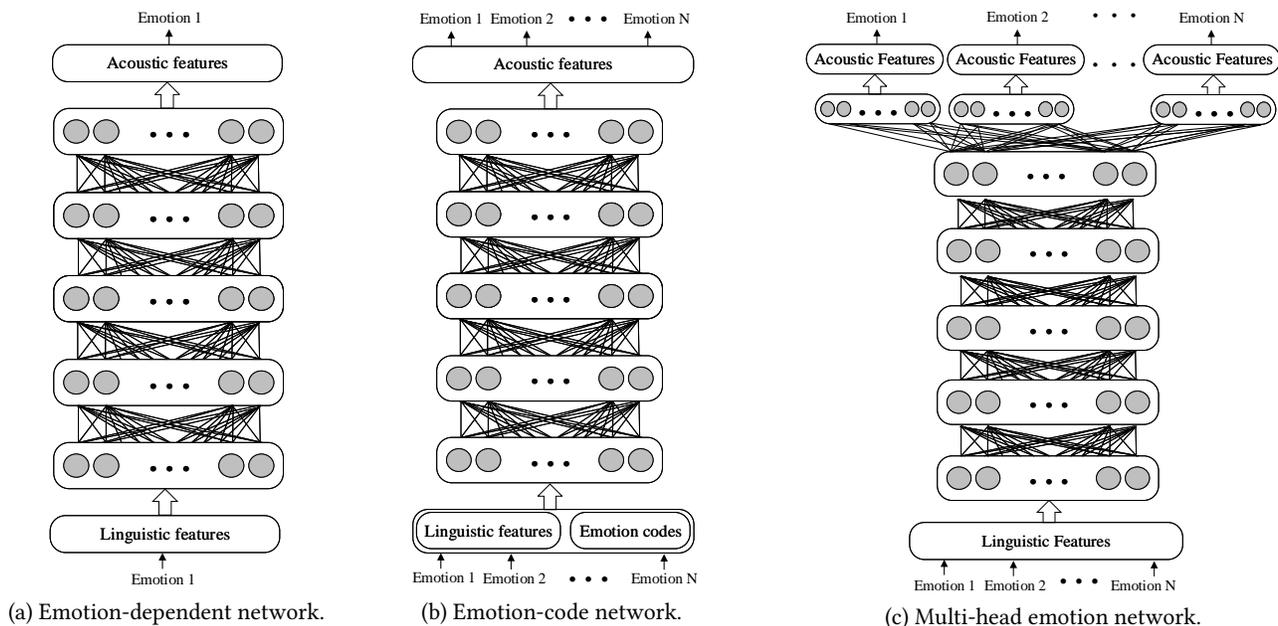


Figure 1: The network structures of three models.

hidden layers. Fan *et al.* [13] proposed a multi-speaker DNN and transferred the hidden layers of the DNN to a new speaker. Later, Li *et al.* [14] presented a multi-language multi-speaker acoustic model using LSTM-RNN.

It is straightforward to migrate from controlling speaker variability to emotional variability. The same approaches used in speaker adaptation may be directly applied for emotion adaptation. In [15], An *et al.* studied two emotional SPSS approaches: retraining a neutral neural network model and adding emotion codes to each layer of the model. Inoue *et al.* [16] investigated how to control speaker variability and emotional variability at the same time. Specifically, three approaches were studied, including a parallel model with an output layer consisting of both speaker-dependent layers and emotion-dependent layers, a serial model with an output layer consisting of emotion-dependent layers preceded by speaker-dependent layers and an auxiliary input model with an input layer consisting of emotion and speaker codes. More recently, Wang *et al.* [17] proposed an unsupervised style modeling approach to control and transfer speaking styles under the end-to-end speech synthesis framework. Although similar to speaker adaptation, emotion adaptation is not trivial because emotional speech has strong prosody variations that are difficult to model [18–20].

In this paper, we present a comprehensive study on the neural network based expressive SPSS. Specifically, we study three typical approaches: retraining a neural model by emotion-specific data (retrain), augmenting the network input using emotion codes (code) and using emotion-dependent output layers with shared hidden layers (multi-head). Long-short term memory (LSTM) [21] networks are used as the acoustic models that map linguistic features to acoustic features. Different from previous approaches, we

provide a study with a variety of emotion styles and test with different size of emotional data. Six typical emotions, i.e., surprise, happiness, sadness, angry, disgust and fear, are investigated and the adaption data size ranges from 10 to 500 utterances. Both objective and subjective evaluations are provided. We have discovered that the multi-head approach consistently outperforms the other two approaches.

The rest of this paper is organized as follows. In Section 2, we introduce the three approaches. Next, we describe a series of experiments and report the results in Section 3. Finally, some conclusions are drawn in Section 4.

2 MODEL DESCRIPTION

2.1 Emotion-dependent Model Retraining

An apparent idea is to retrain a neutral model using emotion-dependent data [22]. The neutral model is usually trained with a large set of data, which provides a good coverage on pronunciations. The small set of emotion-dependent data is used to *fine-tune* the parameters of the neutral model. Figure 1 (a) illustrates such kind of approach, which finally results in an emotion-dependent network for each emotion type.

2.2 Emotion-code Modeling

Augmenting linguistic features with emotion codes as neural network input is another straightforward approach for emotional SPSS. Other approaches, e.g., adding emotion codes to each network layer [15] and using emotion IDs to switch layers for training different emotions [23], can also be considered. But in our model, we simply use a one-hot vector to represent emotion codes. Specifically, we use a 7-dimensional one-hot vector, representing six emotion types and the neutral emotion, respectively. The hidden layers

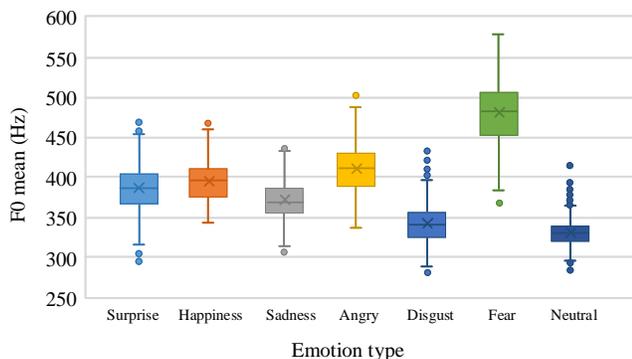


Figure 2: F0 mean distribution for different emotion types.

are shared among all emotion types. The network architecture is illustrated in Figure 1 (b). Figure 2 shows that the fundamental frequency (F0) value varies across different emotions. In [24], Yang *et al.* showed that speaker-dependent normalization could achieve relatively higher speaker similarity scores than the global normalization. Inspired by this, we perform data normalization and de-normalization for each emotion type respectively to take emotion variations into account. In the model training stage, all emotion data are shuffled, and each mini-batch contains data from different emotion categories. In addition, a pre-trained neutral emotion network is used to initialize the parameters.

2.3 Multi-head Emotion Modeling

Another approach is called multi-head emotion modeling, illustrated in Figure 1 (c). This method is motivated by a multi-speaker DNN [13] and the emotion additive model [25]. The input of this network is linguistic features without any auxiliary features. The hidden layers can be regarded as global feature transformation shared across multiple emotions, while the output layers are emotion-dependent, each ‘head’ representing the specific emotion characteristics. Similar with the emotion-code modeling introduced in Section 2.2, we perform data normalization and de-normalization respectively for different emotions.

In the practice, we firstly pre-train a standard neutral-emotion model with single-head output and then expand the model to multiple heads. Specifically, the parameters of the hidden layers of the original single-head network are used to initialize the hidden layers of the new multi-head emotion model. The last-layer parameters of the single-head model are simply copied to each head of the multi-head emotion model as initialization.

Different emotion heads are trained simultaneously under a multi-task learning framework. The training strategy is as follows. For each training epoch, the training data of each emotion is used to calculate an emotion-dependent loss. As for six emotions considered in this study, six losses are obtained in each epoch. Then we calculate the average loss of all the six emotions, which is back propagated to update the parameters of the hidden layers. The emotion-dependent loss is back propagated to each head to update each emotion-dependent output layer. Note that each mini-batch contains data from one emotion type only.

3 EXPERIMENTS

3.1 Experimental Setup

Speech data in Mandarin Chinese from a female professional speaker is used for the experiments. The dataset contains about 10,000 utterances with neutral emotion (standard reading) and 3498 utterances for six emotions (583 utterances each). The emotion types are surprise, happiness, sadness, angry, disgust and fear. We randomly select 500 utterances as the training set, 58 utterances as the validation set, and 25 utterances as the testing set. In the experiments, we vary the size of emotion training data from 10 to 500 to observe the performances. The sampling rate of all waveform files is 16 kHz. The REAPER tool is used to extract F0 in log-scale at a 5-ms step and the STRAIGHT vocoder [26] is used to extract 41-dimensional line spectral pairs (LSP). The final acoustic features are 51-dimensions including 41-dimensional LSP, one extra binary voiced/unvoiced flag and 9-dimensions F0 scores (previous 4 frames, current frame and proceeding 4 frames). Our empirical test shows that modeling F0 context is essential for a stable intonational performance.

As for text analysis, we extract a rich set of textual features including phoneme information, prosodic boundary, state information and the corresponding position index, represented by a 297-dimensional vector with binary and/or numerical features. The state information is obtained by forced alignment using the Hidden Markov Model Toolkit (HTK) [27]. For the neural network input, the only difference between the emotion-code approach and the other two approaches is that the linguistic features are supplemented by the one-hot emotion codes.

For all the tested models, we use bidirectional long short-term memory (BLSTM) based acoustic models. The network structure is three feed-forward layers with 512 nodes, followed by two BLSTM layers with 512 cells and a linear output layer. ReLU is used as the activation function. All systems are optimized using Adam optimizer [28]. The networks are trained using an initial learning rate of 0.0001. All the experiments are carried out using TensorFlow [29].

3.2 Objective Evaluation

Our aim is to use a small set of emotion data to realize decent emotional speech synthesis. Hence we vary the training data size to evaluate the performances of the three approaches. Specifically, LSD distortion (LSD) is measured to evaluate the spectrum distortion, and root mean squared error (RMSE) is used to calculate the F0 prediction error.

LSD and F0 RMSE trajectories are shown in Figure 3 and Figure 4, respectively. From the results, we can see that the multi-head emotion modeling approach achieves lower prediction errors as compared with the other two approaches. The emotion-code modeling approach results in highest LSD and F0 RMSE in most cases. We can also observe that, the changes of LSD curve with different training utterances are relatively steady for three methods. As for F0 RMSE, the emotion-dependent model retraining approach is not stable. For example, the values of F0 RMSE suddenly increase with 20 training utterances for the sadness emotion and the fear emotion. On the contrast, the F0 RMSE of the code approach and the multi-head approach are relatively stable. It indicates that sharing data from different emotion categories is quite helpful.

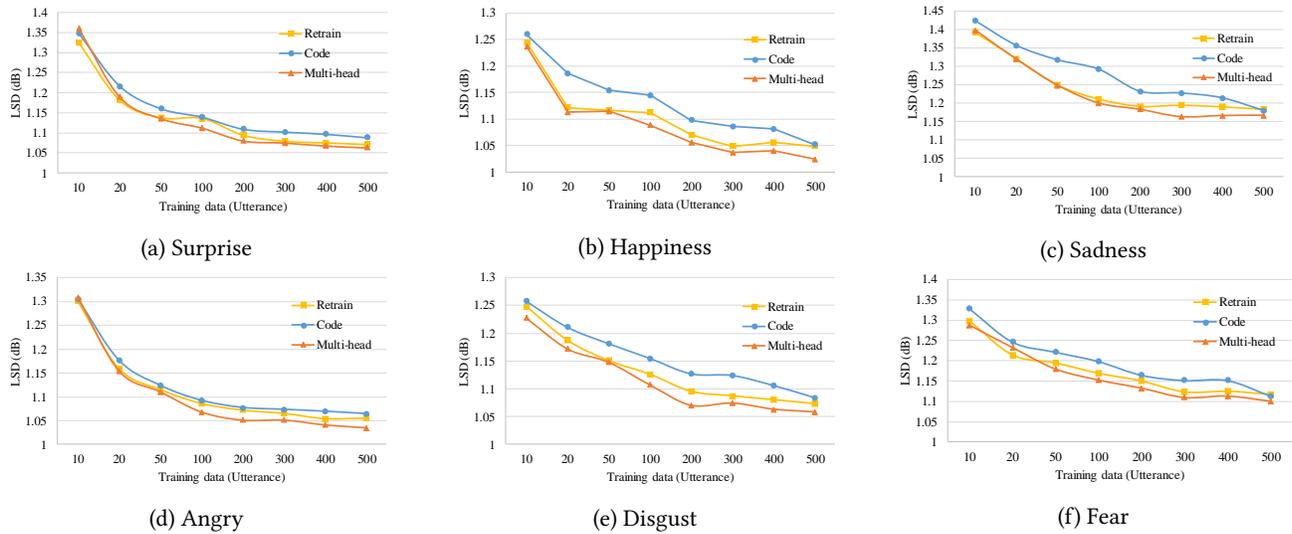


Figure 3: Objective evaluation results of LSD with different amount of training data using three methods for emotions: (a) surprise, (b) happiness, (c) sadness, (d) angry, (e) disgust and (f) fear.

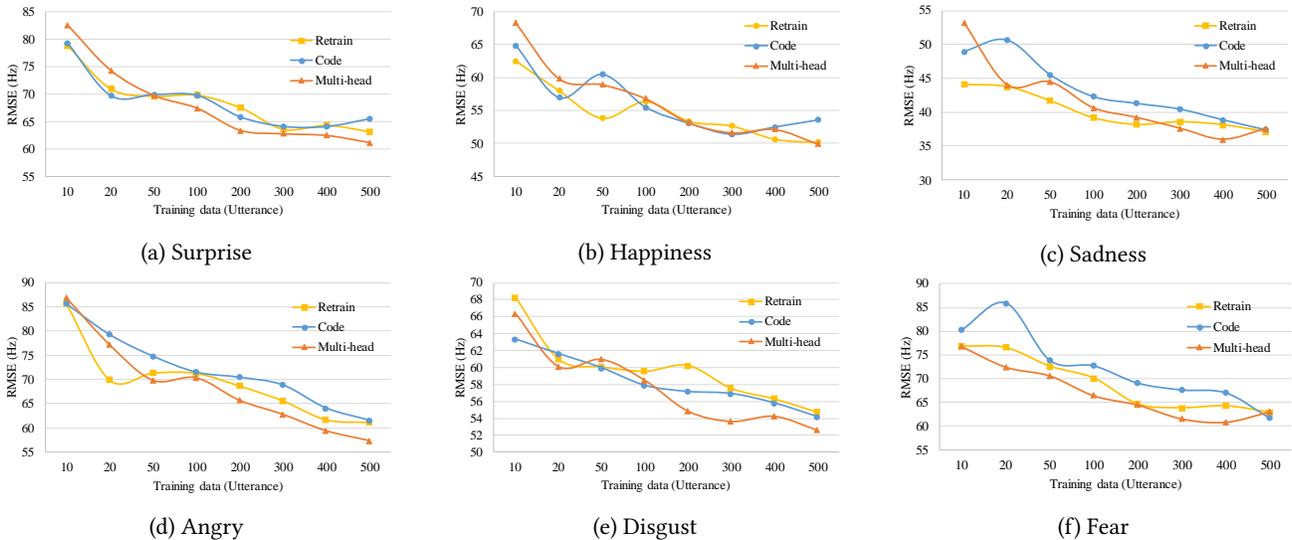


Figure 4: Objective evaluation results of F0 RMSE with different amount of training data using three methods for emotions: (a) surprise, (b) happiness, (c) sadness, (d) angry, (e) disgust and (f) fear.

Obviously, the LSD and F0 RMSE values are decreased as the increase of the training data. But the trend becomes flat when the number of training utterances exceeds 100. The values achieved by the multi-head approach trained using 200 or 300 utterances are similar to those achieved by the code and the retrain approaches trained using 500 utterances. We can notice that LSD and F0 RMSE vary dramatically across different emotions. This is reasonable because different emotions have different acoustic characteristics. For example, as shown in Figure 2 earlier, the F0 values have quite different ranges for different emotion types. This poses significant challenges to expressive speech synthesis.

3.3 Subjective Evaluation

We conduct subjective evaluations using mean opinion score (MOS) tests. The synthesized speech samples are chosen from the three approaches trained using 500 sentences. We randomly select 5 tested sentences for each emotion respectively, resulting in a total of 30 sentences for subjective listening. All the listening samples are presented in a shuffled order. There are 25 native listeners with normal hearing participate in the test. The listeners are asked to rate the overall impression and the expressiveness of the testing samples generated by the three approaches as well as the original recordings.

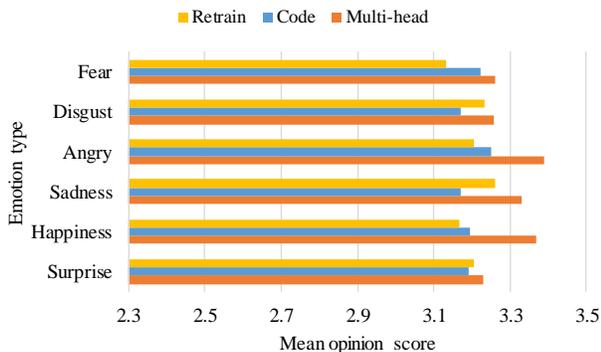


Figure 5: Overall impression results for six emotions.

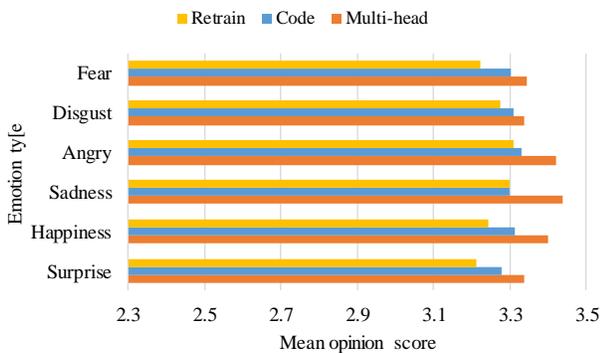


Figure 6: Expressiveness results for six emotions.

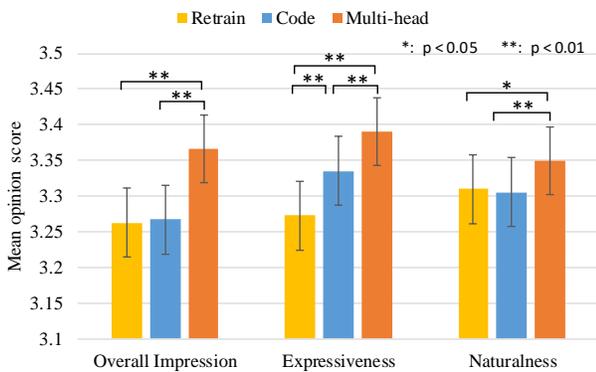


Figure 7: Subjective evaluation results of three methods with 95% confidence interval.

The MOS results for overall impression and the expressiveness for six emotions are summarized in Figure 5 and Figure 6, respectively. From the results, we can clearly see that the multi-head approach performs the best among the three approaches, in terms of both overall impression and expressiveness. The results without

distinguishing emotion categories are further summarized in Figure 7. According to both overall impression and expressiveness, we can conclude that the differences between the multi-head approach and the other two approaches are significant. The performance achieved by the multi-head approach is obviously superior. Listeners have pointed out that, although they can hear clear emotions, the intonation presence of the retrain and emotion-code approaches is not stable and sometimes even unnatural. On the contrast, the multi-head approach always provides stable intonation and more natural speech. The difference among emotions mostly lies in the changes of acoustic features. The multi-head network can effectively make use of the data from all emotions to train the hidden layers while the emotion-dependent output layers are used to represent the acoustic difference among emotions. Thus this approach uses both increased data volume and emotional discrimination.

4 CONCLUSIONS

In this work, we have compared the performances of three emotion adaptation approaches, namely emotion-dependent model retraining, emotion-code modeling and multi-head emotion modeling. Both objective and subjective experiments on six typical emotion types have confirmed that the multi-head emotion modeling approach obtains superior performance. In the future, we will study emotion adaptation under the end-to-end text-to-speech framework [17] [30, 31].

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